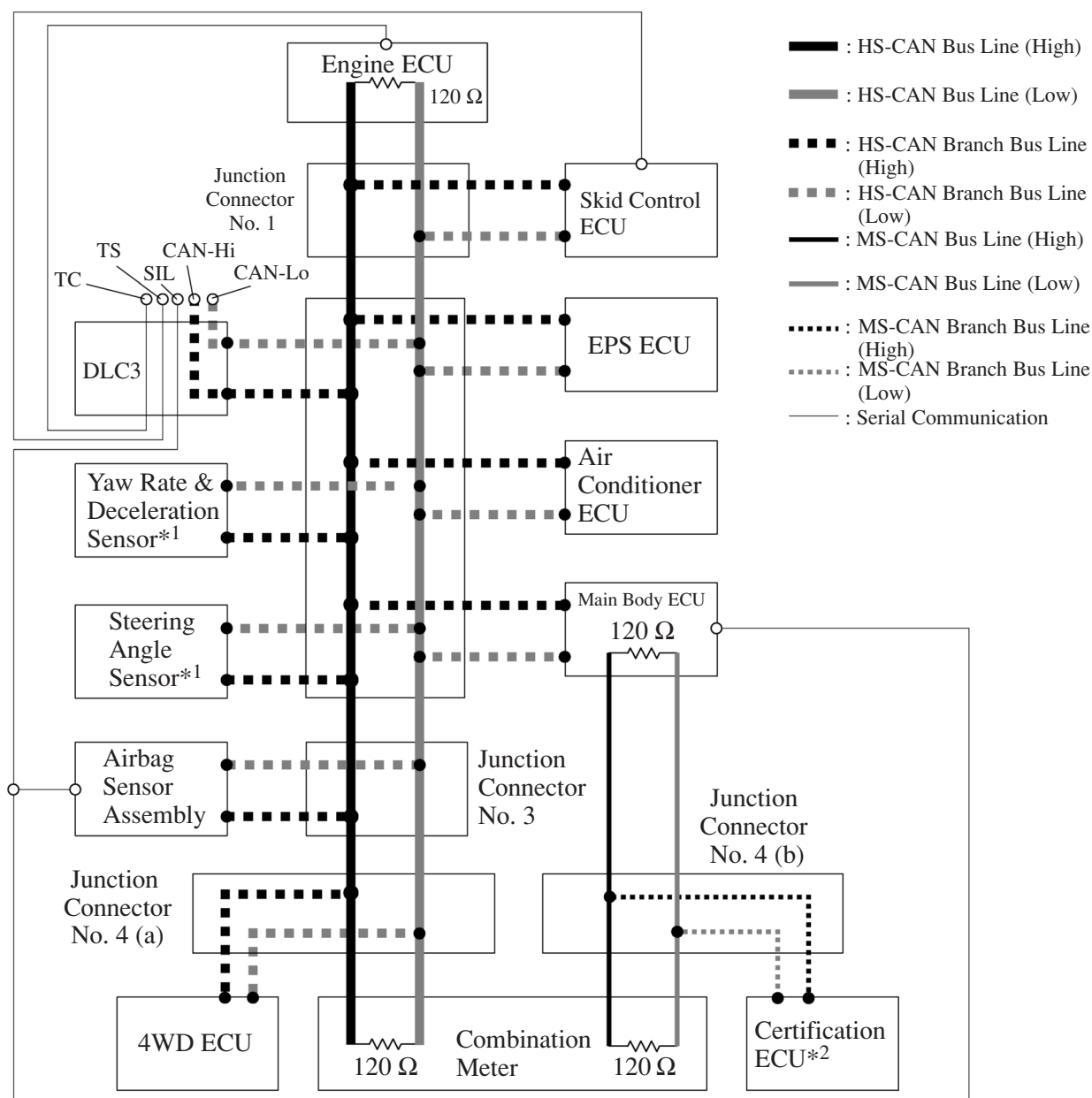


■ CAN (Controller Area Network)

- The CAN (Controller Area Network) is a serial data communication for real time application. It is multiplex communication to be equipped for a vehicle, and has communication 500 kbps speed (main bus line) and 250 kbps speed (medium speed bus line), and the function to detect malfunction.
- The communication wire uses a twisted-pair wire. The bus line has a high line (2.5 V to 3.5 V of voltage is applied) and a low line (1.5 V to 2.5 V of voltage is applied).
- The CAN system in the new model is used to connect the following ECUs and parts via junction connector No. 1, No. 2, No. 3 and No. 4.

► System Diagram ◀



LHD Models

*1: Only for Models with VSC System

*2: Only for Models with Smart Entry & Start System